



*Advancing the Study of Larger
than Life Cellular Automata
with Lua Scripting*

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Outline

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Larger than Life Cellular Automata

- Cellular Automata (CA): A class of discrete, grid-based computational models which are based on simple rules and algorithms
 - Cell states: Typically binary, being either “live” (1) or “dead” (0), and can change states based on states of neighboring cells
- Conway’s Game of Life (*Life*): A CA with simple rules for cell birth, survival, and death, which can lead to dynamic patterns like “spaceships” [1]
- Larger than Life (LtL): A generalization of Life, that extends to larger neighborhoods and uses intervals for birth and survival thresholds [2]
 - Complexity: Allows for exploration of more intricate patterns, such as “bugs”

How can we explore these CA?

Golly is an open-source software for the exploration and simulation of Conway's Game of Life and other cellular automata, including Larger than Life [3]

- Written in C++
- Supports scripting in Python and Lua
- Supports bounded and unbounded universes

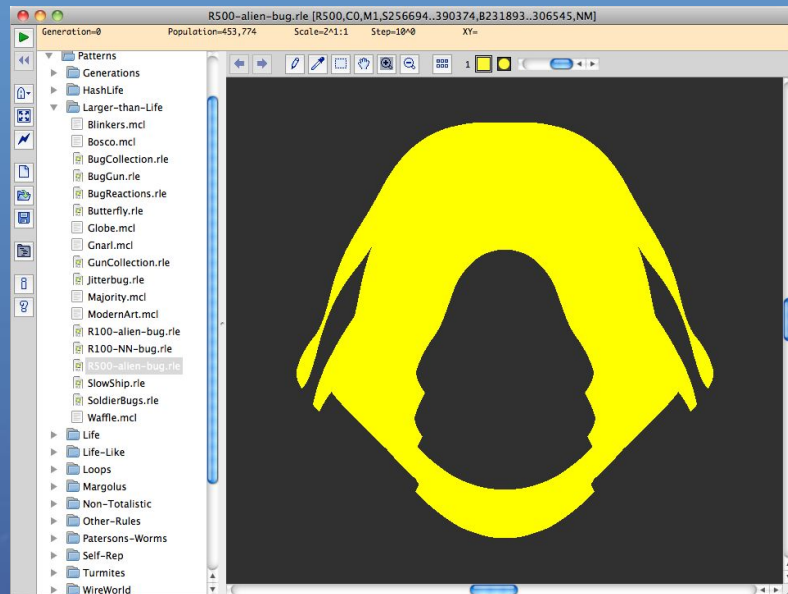


Figure 1: Snapshot of Golly GUI [3]

Motivation

- In *Life*, the most intriguing patterns are known as “spaceships”
 - Can carry information across space as time updates
 - The most famous spaceship is known as a glider
- In LtL, generalizations of *Life*’s spaceships are known as “bugs”
 - Exhibit complex dynamics and behaviors

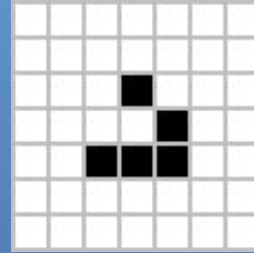


Figure 2: Life's glider [4]

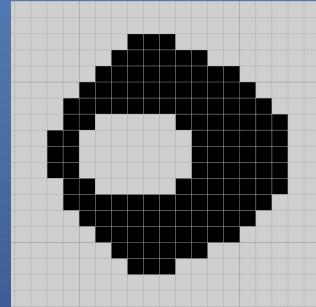


Figure 3: LtL Range 25 Bug

Big Question:

"If cellular automata follow specific rules and algorithms, how can we systematically discover and identify complex patterns like "bugs" within these systems?"

Current Methods for Bug Discovery

- Random Soup Searching
 - “apgsearch” is an automated search program written by Adam P. Goucher [5]
 - Generates large amounts of random asymmetrical soups and runs each soup with a user provided CA rule
- Finite Deterministic Configurations
 - Evans describes the use of geometric initial configurations, such as rectangles and circles, that a rule will “sculpt” into a bug [2] [6]
 - Commonly used and leverages configurations that resemble the geometry of bugs



Figure 4: Glider Emerging from Random Soup

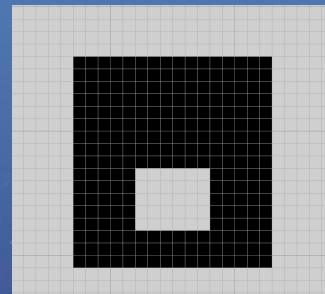


Figure 5: Initial Configuration

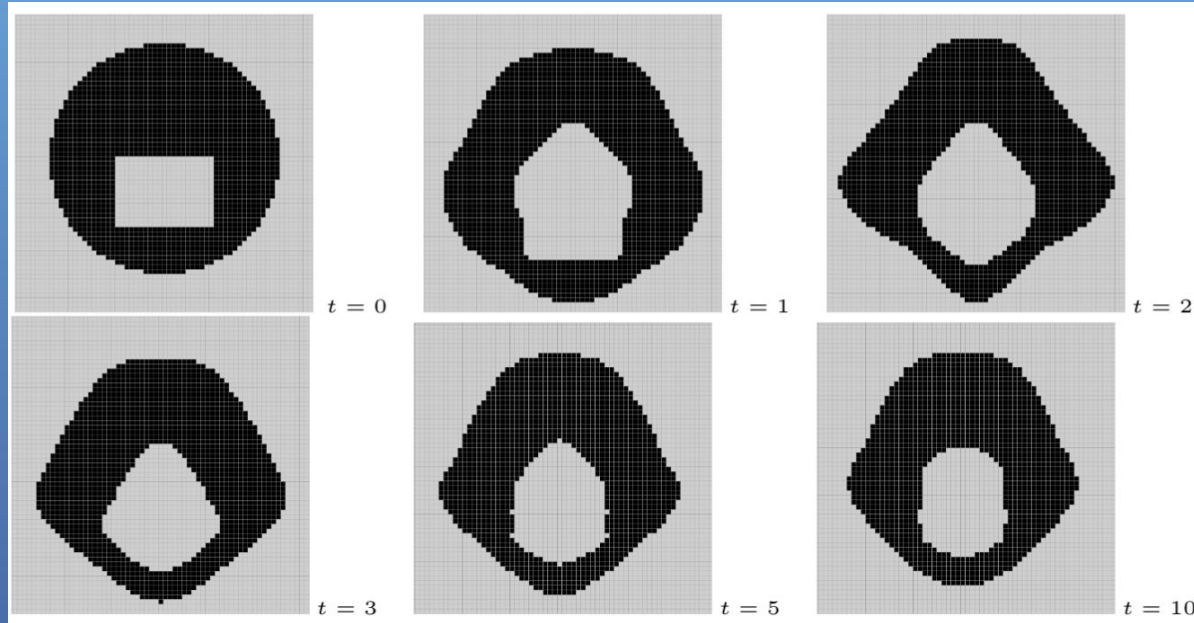


Figure 6: Geometric Initial Configuration

An illustration of a geometric initial configuration sculpted into a bug over time t by the LtL rule with parameters R25,C0,M1,S706..1216,B706..958,NM:

- Dimensions of Initial Configuration:
 - Circle: radius = 24, y - setback = 7, Rectangle: length = 21, width = 15

Scripting Design

A set of Lua scripts has been developed to automate the creation and simulation of geometric initial configurations onto the Golly grid

The most notable script aims to:

- Create and place configurations, based on user-defined parameters, such as:
 - Shape of live and dead sites: circle, rectangle, ellipse
 - Dimensions of shapes: radii, length/width, major/minor axes
 - Vertical “setback” of dead sites: vertical distance from center of live site to center of dead site
- Run a simulation of every configuration created to:
 - Detect surviving patterns, particularly bugs
 - Sort configurations into CSV files, based on their behavior after the simulation has been run, such as patterns that die off

Classifying Patterns: Wolfram's Framework [7]

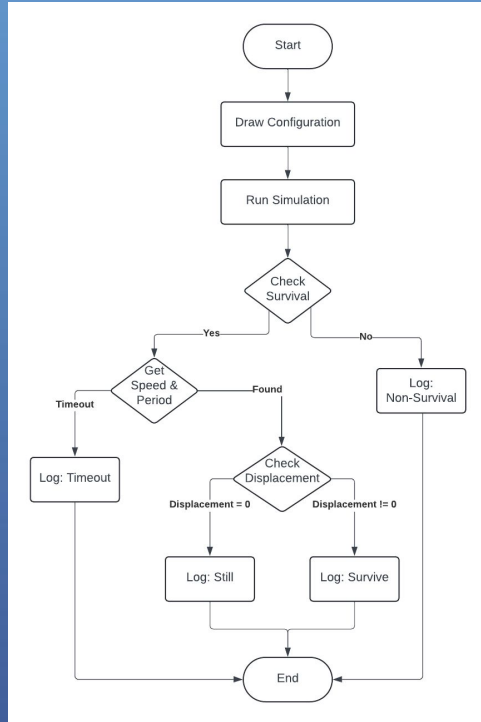


Figure 7: Flowchart of Pattern Classification

- Class 1 (Homogenous States): Dead patterns with no live cells after simulation are classified as non-surviving and logged in "not_survive.csv"
- Class 2 (Periodic Structures): Surviving patterns with no vertical displacement are classified as "still lifes" and logged in "still.csv", while those with displacement are logged in "survive.csv"
- Class 3 (Chaotic Aperiodic Behavior): Patterns that exceed the iteration limit are classified as timeouts and logged in "timeout.csv"
- Class 4 (Complex Localized Structures): Any intricate structures detected during exploration are classified and logged in "survive.csv"

Experimental Results

The following experiment was conducted, based on the user-parameters requested by our Golly-integrated script:

- Name convention for CSV files:
 - Exp1_R25_liveCircle_deadRectangle
- Number of simulation time steps before categorization:
 - 60
- Rule for current grid:
 - R25,C0,M1,S720..1258,B720..978,NM
- Max. iterations in case of runtime error:
 - 1,000
- Shape of live sites:
 - C (circle)
- Bounds of radii
 - 20,25
- Bounds for y-setback
 - 5,15
- Shape of dead sites:
 - R (rectangle)
- Bounds of length/width
 - 17,22 17,22

	B	C	D	E	F	G	H	I	J	K
1	R25,C0,M1,S720..1258,B72 0..978,NM									
2	Dimensions of Live Shape	Y Setback	Shape of Dead Cells	Dimensions of Dead Shape	Period	dy	Population	Bound Box Wd	Bound Box Ht	Hash Value
3	21	6	R	17 17	1	-3	1361	49	49	-565013023
4	21	7	R	17 17	1	-3	1361	49	49	-565013023
5	21	7	R	19 17	1	-3	1361	49	49	-565013023
6	21	8	R	17 17	1	-3	1361	49	49	-565013023
7	21	8	R	17 18	1	-3	1361	49	49	-565013023
8	21	9	R	17 17	1	-3	1361	49	49	-565013023
9	21	9	R	18 17	1	-3	1361	49	49	-565013023
10	21	9	R	19 17	1	-3	1361	49	49	-565013023
11	21	10	R	17 18	1	-3	1361	49	49	-565013023
12	21	10	R	17 19	1	-3	1361	49	49	-565013023
13	21	10	R	18 17	36	-108	1378	48	49	1504284469
14	21	10	R	19 17	1	-3	1361	49	49	-565013023
15	21	10	R	20 17	36	-108	1378	48	49	1504284469
16	21	10	R	21 17	1	-3	1361	49	49	-565013023
17	21	11	R	17 17	1	-3	1361	49	49	-565013023
18	21	11	R	17 20	1	-3	1361	49	49	-565013023
19	21	11	R	19 18	1	-3	1361	49	49	-565013023

Experimental Results

The experiment yielded 2,376 configurations created, simulated, and classified.

- Figure 8 above shows a snapshot of the output of "Exp1_R25_liveCircle_deadRectangle_survive.csv" with 1,163 initial configurations found to sculpt into bugs.

Analysis

Data-Driven Exploration:

- Automating the creation, simulation, and sorting of geometric configurations produced large datasets
- These datasets allow for comprehensive analysis, supporting the formatting and validation of conjectures regarding LtL patterns

Key Insights:

- Understanding the sensitivity of bugs and other life-like patterns to specific initial configurations
- Identifying common traits in configurations that lead to stable or emergent behaviors

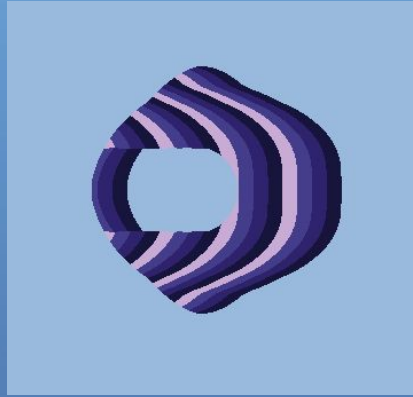
Conclusion

Summary of Key Contributions:

- Introduced an automated method for exploring geometric configurations in Larger than Life cellular automata
- Developed a systematic approach to classify patterns based on their behavior and dynamics
- Generated data to support further conjectures about bug-like patterns and other emergent phenomena and their parameter spaces

Impact and Potential:

- Enables more targeted searches compared to random soup methods, improving pattern recognition
- A foundational approach for the integration of ML for advanced pattern detection



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Thank you!



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